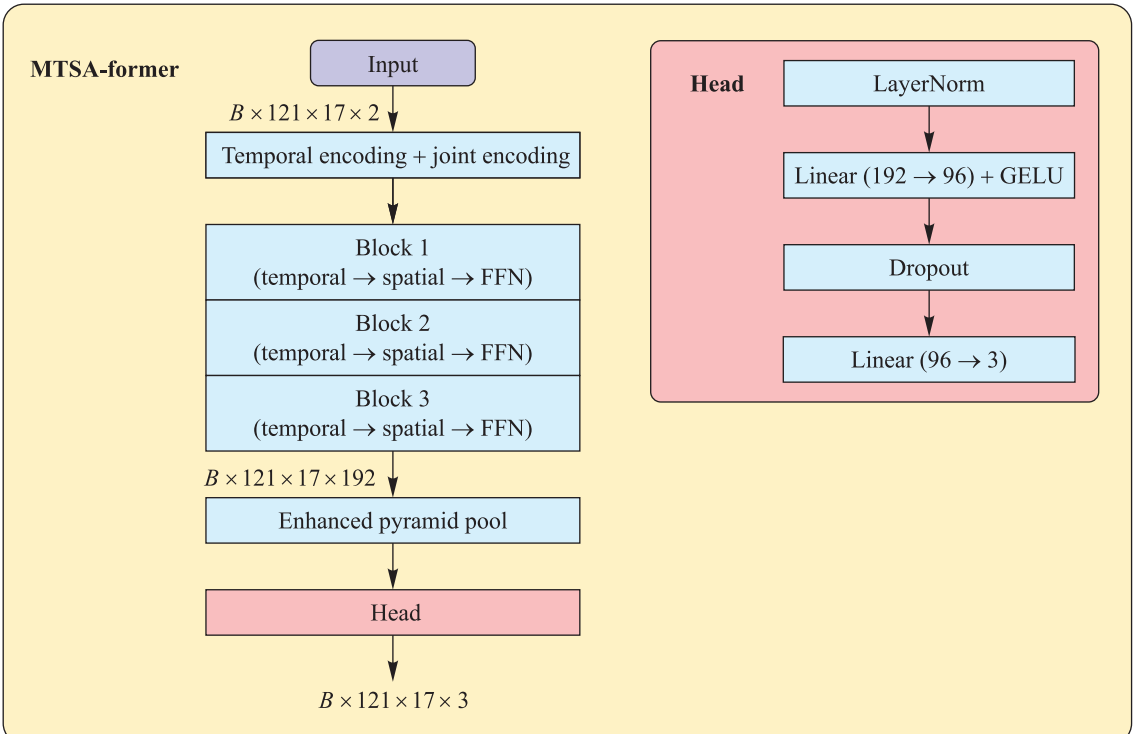

Fig. 3. 3D pose estimation framework using the MTSA-former model