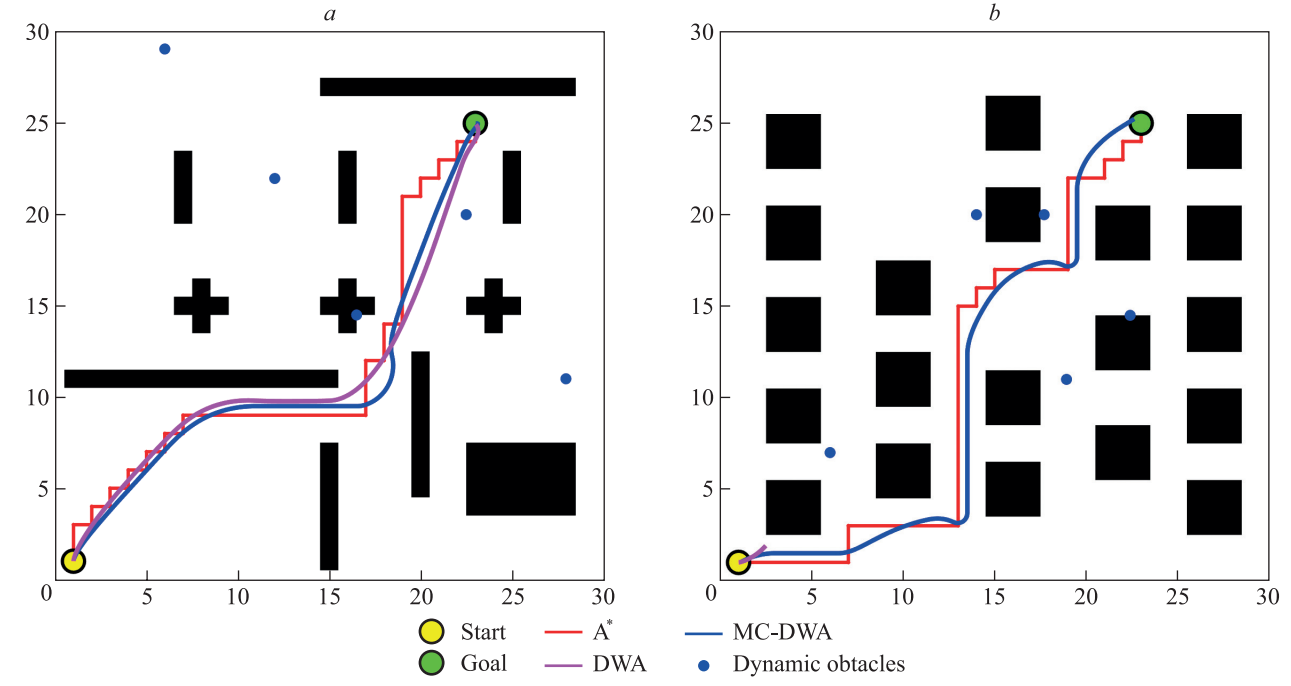


Fig. 2. Visual comparison using classical DWA algorithms and the global A* algorithm on different maps: *a* – normal environment; *b* – dense obstructed environment