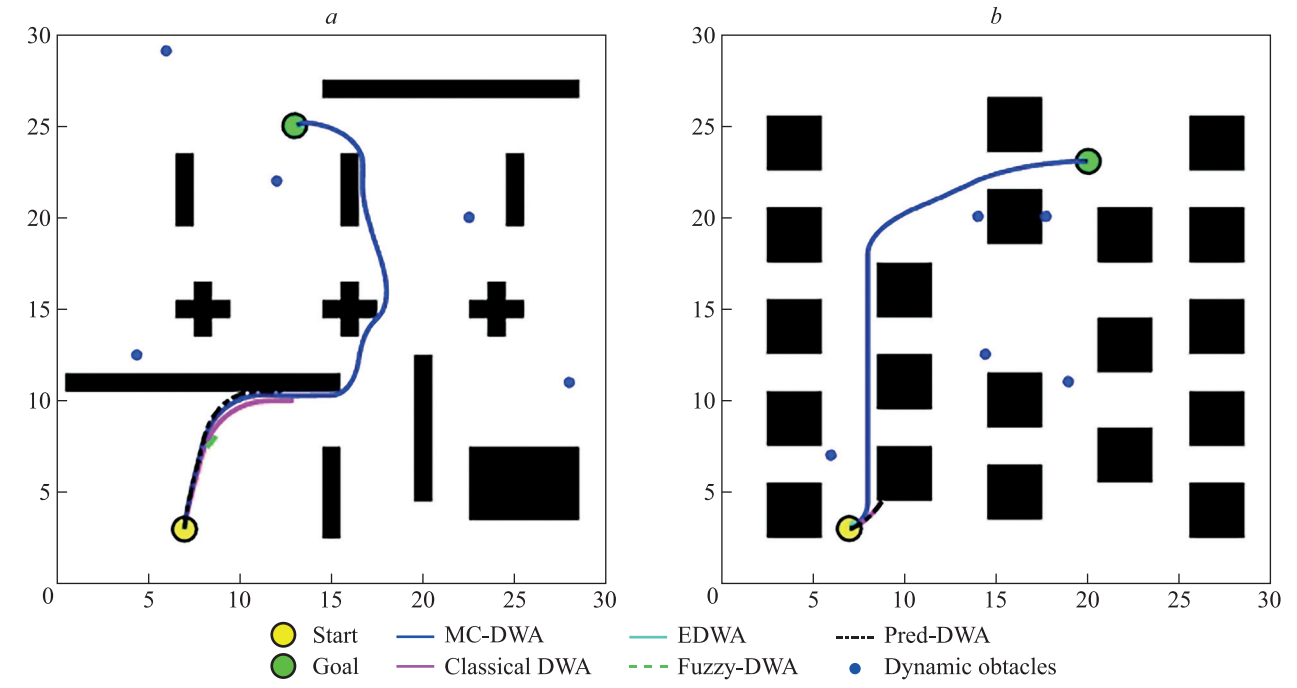


Fig. 3. Visual comparison using different DWA algorithms in complex environments:
a – environment with a distant obstacle; *b* – environment with densely distributed obstacles