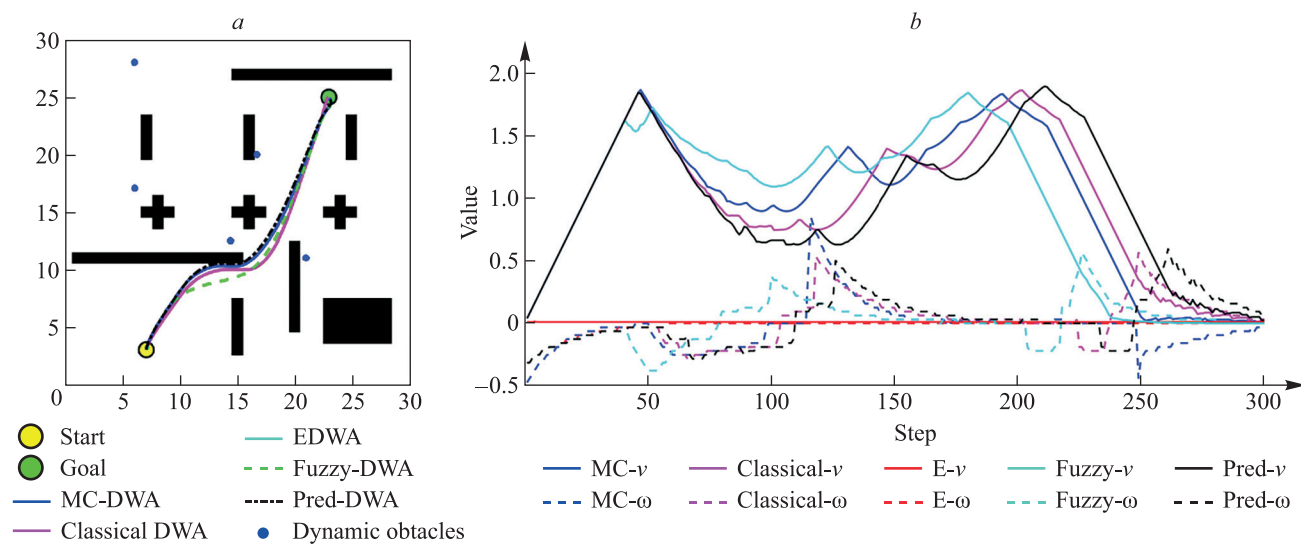


Fig. 4. Dynamic behaviour of various path planning algorithms during execution: *a* – comparison of path planning algorithms; *b* – visualisation of changes in linear and angular speed during the planning process